Recovery of algebraic-exponential data from moments

Jean B. Lasserre

LAAS-CNRS and Institute of Mathematics, Toulouse, France

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* Part of this work is joint with M. Putinar

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Motivation

- An important property of Positively Homogeneous Functions (PHF)
- Some properties (convexity, polarity)
- Sub-level sets of minimum volume containing K
- Exact reconstruction from moments
- Recovery of the defining function of a semi-algebraic set

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Reconstruction of a shape $\mathbf{K} \subset \mathbb{R}^n$ (convex or not)

from knowledge of finitely many moments

$$\mathbf{y}_{\alpha} = \int_{\mathbf{K}} x_1^{\alpha_1} \cdots x_n^{\alpha_n} \, dx, \qquad \alpha \in \mathbb{N}_d^n,$$

for some integer *d*, is a difficult and challenging problem!

EXACT recovery of **K**

from $y = (y_{\alpha}), \alpha \in \mathbb{N}^{n}_{d}$, is even more difficult and challenging!

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Examples of exact recovery:

- Quadrature (planar) Domains in (ℝ²) (Gustafsson, He, Milanfar and Putinar (Inverse Problems, 2000))
 via an exponential transform
- Convex Polytopes (in ℝⁿ) (Gravin, Lasserre, Pasechnik and Robins (Discrete & Comput. Geometry (2012))
 Use Brion-Barvinok-Khovanski-Lawrence-Pukhlikov moment formula for projections ∫_P ⟨c, x⟩^j dx combined with a Prony-type method to recover the vertices of *P*.
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Approximate recovery can de done in multi-dimensions

(Cuyt, Golub, Milanfar and Verdonk, 2005) via :

- (multi-dimensional versions of) homogeneous Padé approximants applied to the Stieltjes transform.
- cubature formula at each point of grid
- solving a linear system of equations to retrieve the indicator function of K

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Exact recovery.

- $\mathbf{K} = \{ x \in \mathbb{R}^n : g(\mathbf{x}) \le 1 \}$ compact.
- g is a nonnegative homogeneous polynomial
- Data are finitely many moments:

$$\mathbf{y}_{lpha} \,=\, \int_{\mathbf{K}} \mathbf{x}^{lpha} \, d\mathbf{x}, \quad lpha \in \mathbb{N}_{d}^{n}.$$

Also works for Quasi-homogeneous polynomials, i.e., when

$$g(\lambda^{u_1}x_1,\ldots,\lambda^{u_n}x_n) = \lambda g(x), \qquad x \in \mathbb{R}^n, \ \lambda > 0$$

for some vector $\boldsymbol{u} \in \mathbb{Q}^n$.

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Another (apparently not well-known) property of PHFs yields surprising and unexpected results, some of them already known in particular cases.

The case of homogeneous polynomials is even more interesting!

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So we are now concerned with PHFs, their sublevel sets and in particular, the integral

$$\mathbf{y} \mapsto \mathbf{I}_{g,h}(\mathbf{y}) := \int_{\{\mathbf{x} : \mathbf{g}(\mathbf{x}) \leq \mathbf{y}\}} h(\mathbf{x}) d\mathbf{x},$$

as a function $I_{g,h} : \mathbb{R}_+ \to \mathbb{R}$ when g, h are PHFs.

With y fixed, we are also interested in

 $\boldsymbol{g}\mapsto \boldsymbol{I_{g,h}(y)},$

now as a function of g, especially when g is a nonnegative homogeneous polynomial.

Nonnegative homogeneous polynomials are particularly interesting as they can be used to approximate norms; see e.g. Barvinok

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Interestingly, the latter integral is related in a simple and remarkable manner to the non-Gaussian integral $\int_{\mathbb{R}^n} h \exp(-g) dx$.

Functional integrals appear frequently in quantum Physics

...... where a challenging issue is to provide

exact formulas for $\int \exp(-g) dx$, the most well-known being when deg g = 2, i.e., $g(\mathbf{x}) = x^T Q x$, with $Q \succ 0$,

$$d = 2 \Rightarrow \int \exp(-g) \, dx = \frac{\operatorname{Cte}}{\sqrt{\operatorname{det}(Q)}}$$

Observe that det(Q) is an algebraic invariant of g,

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The key tools are discriminants and SL(n)-invariants.

An integral

$$J(g) := \int \exp(-g) \, dx$$

is called a discriminant integral.

Next if one write

$$\mathbf{x} \mapsto g(\mathbf{x}) = \sum_{a \in \mathbb{N}^n} g_a \mathbf{x}^a \quad (= \sum_{a \in \mathbb{N}^n} g_a \mathbf{x}_1^{a_1} \cdots \mathbf{x}_n^{a_n}).$$

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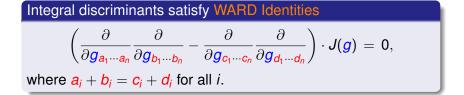
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Next if one write

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which in some (few) low-dimensional cases, permits to obtain exact formulas in terms of algebraic invariants of g. See e.g. Morosov and Shakirov¹

¹New and old results in Resultant theory, arXiv.0911.5278v1.

In particular, as a by-product in the important particular case when h = 1, they have proved that for all *forms g* of degree d,

$$\operatorname{Vol}\left(\{x : g(x) \le 1\}\right) = \int_{\{x : g(x) \le 1\}} dx$$
$$= \operatorname{cte}(d) \cdot \int_{\mathbb{R}^n} \exp(-g) d\mathbf{x},$$

where the constant depends only on *d* and *n*.

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In fact, a formula of exactly the same flavor was already known for convex sets, and was the initial motivation of our work. Namely, if $C \subset \mathbb{R}^n$ is convex, its support function

$$x \mapsto \sigma_{\mathcal{C}}(x) := \sup \{x^T y : y \in \mathcal{C}\},\$$

is a PHF of degree 1, and the polar $C^{\circ} \subset \mathbb{R}^n$ of *C* is the convex set $\{x : \sigma_C(x) \leq 1\}$.

Then ...

$$\operatorname{vol}(\mathcal{C}^{\circ}) = \frac{1}{n!} \int_{\mathbb{R}^n} \exp(-\sigma_{\mathcal{C}}(x)) \, dx, \qquad \forall \mathcal{C}.$$

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I. An important property of PHF's

Let $\phi_1, \phi_2 : \mathbb{R}_+ \to \mathbb{R}$ be measurable mappings, and let $g \ge 0$ and *h* be PHFs of respective degree $0 \neq d, p \in \mathbb{Z}$. We next show that

$$\frac{\int \phi_1(g) h \, d\mathbf{x}}{\int \phi_2(g) h \, d\mathbf{x}} = C(\phi_1, \phi_2, d, p),$$

that is

The ratio DEPENDS ONLY on ϕ_1 , ϕ_2 and the degree of homogeneity of g and h!

With
$$t \mapsto \phi_1(t) = \mathbf{1}_{[0,1]}(t) : \to \int_{\{g(\mathbf{x}) \le 1\}} h(\mathbf{x}) d\mathbf{x}$$
.
With $t \mapsto \phi_2(t) = \exp(-t) : \to \int_{\mathbb{R}^n} h(\mathbf{x}) \exp(-g(\mathbf{x})) d\mathbf{x}$

Theorem

Let $\phi : \mathbb{R}_+ \to \mathbb{R}$ be a measurable mapping, and let $g \ge 0$ and h be PHFs of respective degree $0 \neq d, p \in \mathbb{Z}$ and such that $\int |h| \exp(-g) dx$ is finite,

$$\int_{\mathbb{R}^n} \phi(g(x)) h(x) dx = C(\phi, d, p) \cdot \int_{\mathbb{R}^n} h \exp(-g) dx,$$

where the constant $C(\phi, d, p)$ depends only on ϕ, d, p . In particular, if the sublevel set $\{x : g(x) \le 1\}$ is bounded, then

$$\int_{\{x: g(x) \leq y\}} h \, dx = \frac{y^{(n+p)/d}}{\Gamma(1+(n+p)/d)} \int_{\mathbb{R}^n} h \exp(-g) \, dx,$$

with Γ being the standard Gamma function

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Proof for nonnegative /

For simplicity assume that g(x) > 0 if $x \neq 0$. With $z = (z_1, \ldots, z_{n-1})$, do the change of variable $x_1 = t$, $x_2 = t z_1, \ldots, x_n = t z_{n-1}$ so that one may decompose $\int_{\mathbb{R}^n} \phi(g(x)) h(x) dx$ into the sum

$$\int_{\mathbb{R}_{+}\times\mathbb{R}^{n-1}} t^{n+p-1} \phi(t^{d}g(1,z)) h(1,z) dt dz$$

+
$$\int_{\mathbb{R}_{+}\times\mathbb{R}^{n-1}} t^{n+p-1} \phi(t^{d}g(-1,-z)) h(-1,z) dt dz,$$

=
$$\int_{\mathbb{R}^{n-1}} \left(\int_{0}^{\infty} t^{n+p-1} \phi(t^{d}g(1,z)) dt \right) h(1,z) dz$$

+
$$\int_{\mathbb{R}^{n-1}} \left(\int_{0}^{\infty} t^{n+p-1} \phi(t^{d}g(-1,-z)) dt \right) h(-1,-z) dz,$$

where the last two integrals are obtained from the sum of the previous two by using Tonelli's Theorem.

Proof (continued)

Next, with the change of variable $u = t g(1, z)^{1/d}$ and $u = t g(-1, -z)^{1/d}$

$$\int_{\mathbb{R}^n} \phi(g(x)) h(x) dx = \underbrace{\left(\int_{\mathbb{R}_+} u^{n+p-1} \phi(u^d) du\right)}_{\operatorname{Cte}(\phi, p, d)} \cdot A(g, h),$$

with

$$A(g,h) = \int_{\mathbb{R}^{n-1}} \left(\frac{h(1,z)}{g(1,z)^{(n+p)/d}} + \frac{h(-1,-z)}{g(-1,-z)^{(n+p)/d}} \right) dz.$$

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Choosing
$$\phi(t) = \exp(-t)$$
 on $[0, +\infty)$ yields:

$$\int_{\mathbb{R}^n} \exp(-g(x)) h(x) dx = \frac{\Gamma(1 + (n+p)/d)}{n+p} \cdot A(g, h),$$

whereas, choosing
$$\phi(\cdot) = I_{[0,1]}(t)$$
 on $[0, +\infty)$ yields:
$$\int_{\{x : g(x) \le 1\}} h(x) \, dx = \frac{1}{n+p} \cdot A(g,h),$$

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Jean B. Lasserre Recovery of algebraic-exponential data from moments

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And so in particular, whenever g is nonnegative and $\{x : g(x) \le 1\}$ has finite Lebesgue volume:

Theorem

If g, h are PHFs of degree 0 < d and p respectively, then:

$$\int_{\{x:g(x)\leq y\}} h dx = \frac{y^{(n+p)/d}}{\Gamma(1+(n+p)/d)} \int_{\mathbb{R}^n} \exp(-g) h dx$$

$$\operatorname{vol}\left(\{x : g(x) \leq y\}\right) = \frac{y^{n/d}}{\Gamma(1+n/d)} \int_{\mathbb{R}^n} \exp(-g) \, dx$$

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An alternative proof

Let g, h be nonnegative so that $I_{g,h}(y)$ vanishes on $(-\infty, 0]$. For $0 < \lambda \in \mathbb{R}$, its Laplace transform $\lambda \mapsto \mathcal{L}_{I_{g,h}}(\lambda) = \int_0^\infty \exp(-\lambda y) I_{g,h}(y) \, dy$ reads:

$$\mathcal{L}_{l_{g,h}}(\lambda) = \int_{0}^{\infty} \exp(-\lambda y) \left(\int_{\{x:g(x) \le y\}}^{\infty} h dx \right) dy$$

$$= \int_{\mathbb{R}^{n}} h(x) \left(\int_{g(x)}^{\infty} \exp(-\lambda y) dy \right) dx \quad [by Fubini]$$

$$= \frac{1}{\lambda} \int_{\mathbb{R}^{n}} h(x) \exp(-\lambda g(x)) dx$$

$$= \frac{1}{\lambda^{1+(n+p)/d}} \int_{\mathbb{R}^{n}} h(z) \exp(-g(z)) dz \quad [by homog]$$

$$= \frac{\int_{\mathbb{R}^{n}} h(z) \exp(-g(z)) dz}{\Gamma(1+(n+p)/d)} \mathcal{L}_{y^{(n+p)/d}}(\lambda).$$

And so, by analyticity and the Identity theorem of analytical functions

$$I_{g,h}(\mathbf{y}) = \frac{\mathbf{y}^{(n+p)/d}}{\Gamma(1+(n+p)/d)} \int_{\mathbb{R}^n} h(x) \exp(-g(x)) dx,$$

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II. Approximating a non gaussian integral

Hence computing the non Gaussian integral $\int \exp(-g) dx$

reduces to computing the volume of the level set $G := \{x : g(x) \le 1\},\$

... which is the same as solving the optimization problem:

$$\max_{\mu} \quad \mu(G)$$

s.t.
$$\mu + \nu = \lambda$$
$$\mu(\mathbf{B} \setminus G) = 0$$

where :

- **B** is a box $[-a, a]^n$ containing **G** and
- λ is the Lebesgue measure.

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... and we know how to

approximate as closely as desired $\mu(G)$ and any FIXED number of moments of μ , by solving an appropriate hierarchy of semidefinite programs (SDP).

(see: *Approximate volume and integration for basic semi algebraic sets*, Henrion, Lasserre and Savorgnan, SIAM Review 51, 2009.)

However . .

the resulting SDPs are numerically difficult to solve.

Solving the dual reduces to approximating the indicator function I(G) by polynomials of increasing degrees \rightarrow Gibbs effect, etc.

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Let $G \subseteq \mathbf{B} := [-1, 1]^n$ (possibly after scaling), and let $z = (z_\alpha)$, $\alpha \in \mathbb{N}^n_{2k}$, be the moments of the Lebesgue measure λ on B.

Solve the hierarchy of semidefinite programs:

$$\rho_{k} = \max \quad \mathbf{y}_{0}$$

s.t.
$$\mathbf{M}_{k}(\mathbf{y}), \mathbf{M}_{k}(\mathbf{v}) \succeq 0,$$
$$\mathbf{M}_{k-\lceil (d)/2 \rceil}(\mathbf{g} \mathbf{y}) \succeq 0$$
$$\mathbf{M}_{k-1}((1-x_{i}^{2}) \mathbf{v}) \succeq 0, \quad i = 1, \dots, n$$
$$\mathbf{y}_{\alpha} + \mathbf{v}_{\alpha} = \mathbf{z}_{\alpha}, \quad \alpha \in \mathbb{N}_{2k}^{n}$$

for some moment and localizing matrices $\mathbf{M}_k(\mathbf{y})$ and $\mathbf{M}_k(\mathbf{g}, \mathbf{y})$. • The linear constraints $\mathbf{y}_{\alpha} + \mathbf{v}_{\alpha} = \mathbf{z}_{\alpha}$ for all $\alpha \in \mathbb{N}_{2k}^n$ "ensure" $\mu + \nu = \lambda$, while the " \succeq 0" constraints "ensure" supp $\mu = \mathbf{G}$ and supp $\nu = \mathbf{B}$.

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$$\mathbf{M}_{k-1}((1 - x_{i}^{2}) \mathbf{v}) \succeq 0, \quad i = 1, \dots, n$$
$$\mathbf{y}_{\alpha} + \mathbf{v}_{\alpha} = \mathbf{z}_{\alpha}, \quad \alpha \in \mathbb{N}_{2k}^{n}$$

for some moment and localizing matrices $\mathbf{M}_k(\mathbf{y})$ and $\mathbf{M}_k(\mathbf{g}, \mathbf{y})$. • The linear constraints $\mathbf{y}_{\alpha} + \mathbf{v}_{\alpha} = \mathbf{z}_{\alpha}$ for all $\alpha \in \mathbb{N}_{2k}^n$ "ensure" $\mu + \nu = \lambda$, while the " $\succeq 0$ " constraints "ensure" supp $\mu = \mathbf{G}$ and supp $\nu = \mathbf{B}$.

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Another identity

Corollary

If g has degree d and G has finite volume then

$$\frac{\int_{\{x:g(x)\leq y\}} \exp(-g) dx}{\int_{\mathbb{R}^n} \exp(-g) dx} = \frac{\int_0^y t^{n/d-1} \exp(-t) dt}{\int_0^\infty t^{n/d-1} \exp(-t) dt}$$
$$= \frac{\int_0^y t^{n/d-1} \exp(-t) dt}{\Gamma(n/d)}$$

expresses how fast $\mu(\{x : g(x) \le y\})$ goes to $\mu(\mathbb{R}^n)$ as $y \to \infty$, for the Borel measure $d\mu = \exp(-g) dx$.

It is like for the Gamma function $\Gamma(n/d)$ when approximated by $\int_0^y t^{n/d-1} \exp(-t) dt$.

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III. Convexity

An interesting issue is to analyze how the Lebesgue volume $\operatorname{vol} \{x \in \mathbb{R}^n : g(x) \leq 1\}$, (i.e. $\operatorname{vol} (G)$) changes with g.

Corollary

Let *h* be a PHF of degree *p* and let $C_d \subset \mathbb{R}[x]_d$ be the convex cone of homogeneous polynomials *g* of degree at most *d* such that $\int_G |h| dx < \infty$. Then the function $f_h : C_d \to \mathbb{R}$,

$$g\mapsto f_h(g):=\int_G h\,dx,\qquad g\in C_d,$$

- is a PHF of degree -(n + p)/d,
- convex whenever h is nonnegative and strictly convex if h > 0 on ℝⁿ \ {0}

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Corollary (continued)

Moreover, if h is continuous and $g \in int(C_d)$ then:

$$\frac{\partial f_h(g)}{\partial g_\alpha} = \frac{-1}{\Gamma(1+(n+p)/d)} \int_{\mathbb{R}^n} x^\alpha h \exp(-g) dx$$
$$= \frac{-\Gamma(2+(n+p)/d)}{\Gamma(1+(n+p)/d)} \int_G x^\alpha h dx$$
$$\frac{\partial^2 f_h(g)}{\partial g_\alpha \partial g_\beta} = \frac{-1}{\Gamma(1+(n+p)/d)} \int_{\mathbb{R}^n} x^{\alpha+\beta} h \exp(-g) dx$$

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PROOF: Just use

$$\int_{\{x: g(x) \le 1\}} h \, dx = \frac{1}{\Gamma(1 + (n + p)/d)} \int_{\mathbb{R}^n} h \exp(-g) \, dx$$

Notice that proving convexity directly would be non trivial but becomes easy when using the previous lemma!

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Notice that proving convexity directly would be non trivial but becomes easy when using the previous lemma!

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For a set $C \subset \mathbb{R}^n$, recall:

• The support function $x \mapsto \sigma_{C}(x) := \sup_{y \in C} \{x^{T}y : y \in C\}$

• The POLAR $C^{\circ} := \{x \in \mathbb{R}^n : \sigma_C(x) \leq 1\}$

• and for a PHF *g* of degree *d*, its Legendre-Fenchel conjugate $g^*(x) = \sup_{y} \{x^T y - g(y)\}$ is a PHF of degree *q* with $\frac{1}{d} + \frac{1}{q} = 1$.

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Polarity (continued)

Lemma

Let g be a closed proper convex PHF of degree 1 < d and let $G = \{x : g(x) \le 1/d\}$. Then:

$$G^{\circ} = \{x \in \mathbb{R}^{n} : g^{*}(x) \leq 1/q\}$$

$$vol(G) = \frac{p^{-n/p}}{\Gamma(1+n/p)} \int exp(-g) dx$$

$$vol(G^{\circ}) = \frac{q^{-n/q}}{\Gamma(1+n/q)} \int exp(-g^{*}) dx$$

 \rightarrow yields completely symmetric formulas for g and its conjugate g^* .

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Examples

•
$$g(x) = |x|^3$$
 so that $g^*(x) = \frac{2}{3\sqrt{3}}|x|^{3/2}$. And so
 $G = [-3^{-1/3}, 3^{-1/3}]; \quad G^\circ = [-3^{1/3}, 3^{1/3}].$

• TV screen:
$$g(x) = x_1^4 + x_2^4$$
 so that $g^*(x) = 4^{-4/3} \Im(x_1^{4/3} + x_2^{4/3})$. And,

$$\mathbf{G} = \{x: x_1^2 + x_2^4 \leq \frac{1}{4}\}; \quad \mathbf{G}^\circ = \{x: x_1^{4/3} + x_2^{4/3} \leq 4^{1/3}\}.$$

• g(x) = |x| so that $d \ge 1$, and $g^*(x) = 0$ if $x \in [-1, 1]$, and $+\infty$ otherwise. Hence $G = \{x : |x| \le 1\} = [-1, 1]$ and with $q = +\infty$,

$$G^{\circ} = [-1, 1] = \{x : g^{*}(x) \leq \frac{1}{q} = 0\}.$$

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IV. A variational property of homogeneous polynomials

Let $\mathbf{v}_d(x)$ be the vector of monomials (x^{α}) of degree d, i.e., such that $\alpha_1 + \cdots + \alpha_n = d$. (And so $\mathbf{v}_1(x) = x$.) If $g \in \mathbb{R}[x]_{2d}$ is homogeneous and SOS then

$$g(x) = \frac{1}{2} \mathbf{v}_d(x)^T \boldsymbol{\Sigma} \mathbf{v}_d(x),$$

for some real symmetric positive definite matrix $\Sigma \succ 0$.

And if d = 1 one has the Gaussian property

$$\int_{\mathbb{R}^n} \exp(-g) \, dx = \frac{(2\pi)^{n/2}}{\sqrt{\det \Sigma}},$$
$$\frac{\int_{\mathbb{R}^n} \mathbf{v}_d(x) \, \mathbf{v}_d(x)^T \, \exp(-g) \, dx}{\int_{\mathbb{R}^n} \exp(-g) \, dx} = \Sigma^{-1}.$$

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$$\boldsymbol{g}(\boldsymbol{x}) = \frac{1}{2} \boldsymbol{v}_d(\boldsymbol{x})^T \boldsymbol{\Sigma} \boldsymbol{v}_d(\boldsymbol{x}),$$

for some real symmetric positive definite matrix $\Sigma \succ 0$.

And if
$$d = 1$$
 one has the Gaussian property

$$\int_{\mathbb{R}^{n}} \exp(-g) \, dx = \frac{(2\pi)^{n/2}}{\sqrt{\det \Sigma}},$$

$$\frac{\int_{\mathbb{R}^{n}} \mathbf{v}_{d}(x) \, \mathbf{v}_{d}(x)^{T} \, \exp(-g) \, dx}{\int_{\mathbb{R}^{n}} \exp(-g) \, dx} = \Sigma^{-1}.$$

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In other words, if μ is the Gaussian measure

$$\mu(B) := \frac{\int_{B} \exp\left(-\frac{1}{2}x^{T}\Sigma x\right) dx}{\int_{\mathbb{R}^{n}} \exp\left(-\frac{1}{2}x^{T}\Sigma x\right) dx}, \quad \forall B,$$

then its (covariance) matrix of moments of order 2 satisfies:

$$\mathbf{M}_{1}(\boldsymbol{\Sigma}) := \int_{\mathbb{R}^{n}} x \, x^{T} \, \boldsymbol{d} \boldsymbol{\mu}(x) = \boldsymbol{\Sigma}^{-1},$$

and the function

$$\theta_1(\boldsymbol{\Sigma}) := (\det \boldsymbol{\Sigma})^{1/2} \int_{\mathbb{R}^n} \exp\left(-\frac{1}{2} \mathbf{v}_1(x)^T \boldsymbol{\Sigma} \, \mathbf{v}_1(x)\right) \, dx.$$

is constant!

... not true anymore for d > 1!

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However, let $\ell(d) = \binom{n+d-1}{d}$, and $\mathcal{S}_{++}^{\ell(d)}$ be the cone of real positive definite $\ell(d) \times \ell(d)$ matrices. Let $k := n/(2d\ell(d))$.

With $\Sigma \in \mathcal{S}_{++}^{\ell(d)}$, define the probability measure μ

$$\mu(B) := \frac{\int_{B} \exp\left(-k\mathbf{v}_{d}(x)^{T} \mathbf{\Sigma} \mathbf{v}_{d}(x)\right) dx}{\int_{\mathbb{R}^{n}} \exp\left(-k\mathbf{v}_{d}(x)^{T} \mathbf{\Sigma} \mathbf{v}_{d}(x)\right) dx}, \quad \forall B$$

with matrix of moments of order 2d given by:

$$\mathbf{M}_d(\boldsymbol{\Sigma}) := \int_{\mathbb{R}^n} \mathbf{v}_d(x) \, \mathbf{v}_d(x)^T \, \boldsymbol{d}\mu(x).$$

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Define $\theta_d : \mathcal{S}_{++}^{\ell(d)} \to \mathbb{R}$ to be the function

$$\boldsymbol{\Sigma} \mapsto \theta_d(\boldsymbol{\Sigma}) := (\det \boldsymbol{\Sigma})^k \int_{\mathbb{R}^n} \exp\left(-k \mathbf{v}_d(x)^T \boldsymbol{\Sigma} \, \mathbf{v}_d(x)\right) \, dx.$$

Theorem

$$\mathbf{M}_{d}(\mathbf{\Sigma}) = \mathbf{\Sigma}^{-1} \iff \nabla \theta_{d}(\mathbf{\Sigma}) = \mathbf{0}$$

Hence critical points Σ^* of θ_d have the Gaussian property

$$\frac{\int \mathbf{v}_d(x) \mathbf{v}_d(x)^T \exp\left(-k \mathbf{v}_d(x)^T \mathbf{\Sigma}^* \mathbf{v}_d(x)\right) dx}{\int \exp\left(-k \mathbf{v}_d(x)^T \mathbf{\Sigma}^* \mathbf{v}_d(x)\right) dx} = (\mathbf{\Sigma}^*)^{-1}$$

* If d = 1 then $\theta_d(\cdot)$ is constant and so $\nabla \theta_d(\cdot) = 0$. * If d > 1 then $\theta_d(\cdot)$ is constant in each ray $\lambda \Sigma$, $\lambda > 0$.

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$$\nabla \theta_{d}(\Sigma) = k \frac{\Sigma^{\mathbb{A}}}{\det \Sigma} \theta_{d}(\Sigma)$$
$$-k(\det \Sigma)^{k} \int_{\mathbb{R}^{n}} \mathbf{v}_{d}(x) \mathbf{v}_{d}(x)^{T} \exp\left(-k \mathbf{v}_{d}(x)^{T} \Sigma \mathbf{v}_{d}(x)\right) dx$$
$$= k \theta_{d}(\Sigma) \left[\Sigma^{-1} - \mathbf{M}_{d}(\Sigma)\right]$$

and so

$$\mathbf{M}_d(\Sigma) = \Sigma^{-1} \quad \Rightarrow \quad \nabla \theta_d(\Sigma) = 0.$$

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If $\mathbf{K} \subset \mathbb{R}^n$ is compact then computing the ellipsoid ξ of minimum volume containing \mathbf{K} is a classical problem whose optimal solution is called the Löwner-John ellipsoid. So consider the following problem:

Find an homogeneous polynomial $g \in \mathbb{R}[x]_{2d}$ such that its sub level set $G := \{x : g(x) \le 1\}$ contains K and has minimum volume among all such levels sets with this inclusion property.

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Let $\mathbf{P}[x]_{2d}$ be the convex cone of homogeneous polynomials of degree 2d whose sub-level set $\mathbf{G} = \{x : g(x) \le 1\}$ has finite Lebesgue volume and with $\mathbf{K} \subset \mathbb{R}^n$, let $C_{2d}(\mathbf{K})$ be the convex cone of polynomials nonnegative on \mathbf{K} .

Lemma

Let $\mathbf{K} \subset \mathbb{R}^n$ be compact. The minimum volume of a sublevel set $\mathbf{G} = \{\mathbf{x} : g(\mathbf{x}) \leq 1\}, g \in \mathbf{P}[x]_{2d}$, that contains $\mathbf{K} \subset \mathbb{R}^n$ is $\rho/\Gamma(1 + n/2d)$ where:

$$\mathcal{P}: \qquad \rho = \inf_{g \in \mathbf{P}[x]_{2d}} \left\{ \int_{\mathbb{R}^n} \exp(-g) \, dx \, : \, 1 - g \, \in \, C_{2d}(\mathbf{K}) \right\}$$

a finite-dimensional convex optimization problem!

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a finite-dimensional convex optimization problem!

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Proof

• We have seen that:

$$\operatorname{vol}(\{x : g(x) \leq 1\}) = \frac{1}{\Gamma(1 + n/2d)} \int_{\mathbb{R}^n} \exp(-g) \, dx.$$

Moreover, the sub-level set $\{x : g(x) \le 1\}$ contains **K** if and only if $1 - g \in C_{2d}(\mathbf{K})$, and so $\rho/\Gamma(1 + n/2d)$ is the minimum value of all volumes of sub-levels sets $\{x : g(x) \le 1\}$, $g \in \mathbf{P}[\mathbf{x}]_{2d}$, that contain **K**.

• Now since $g \mapsto \int_{\mathbb{R}^n} \exp(-g) dx$ is strictly convex and $C_{2d}(\mathsf{K})$ is a convex cone, problem \mathcal{P} is a finite-dimensional convex optimization problem. \Box

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V (continued). Characterizing an optimal solution

Theorem

(a) \mathcal{P} has a unique optimal solution $g^* \in \mathbf{P}[x]_{2d}$ and if $g^* \in \operatorname{int}(\mathbf{P}[x]_{2d})$ there exists a Borel measure μ^* supported on **K** such that:

(*):
$$\begin{cases} \int_{\mathbb{R}^n} x^{\alpha} \exp(-g^*) dx = \int_{\mathbf{K}} x^{\alpha} d\mu^*, \quad \forall |\alpha| = 2d \\ \int_{\mathbf{K}} (1 - g^*) d\mu^* = 0 \end{cases}$$

In particular, μ^* is supported on the real variety $V := \{x \in \mathbf{K} : g^*(\mathbf{x}) = 1\}$ and in fact, μ^* can be substituted with another measure ν^* supported on at most $\binom{n+2d-1}{2d}$ points of V.

(b) Conversely, if $g^* \in int(\mathbf{P}[x]_{2d})$ and μ^* satisfy (*) then g^* is an optimal solution of \mathcal{P} .

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Let $\mathbf{K} \subset \mathbb{R}^2$ be the box $[-1, 1]^2$.

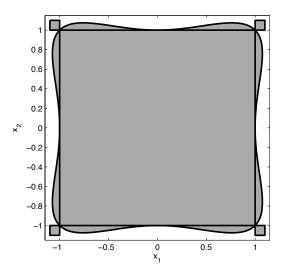
The set $G_4 := \{x : g(x) \le 1\}$ with *g* homogeneous of degree 4 which contains **K** and has minimum volume is

$$\mathbf{x}\mapsto \mathbf{g}_4(\mathbf{x}):=x_1^4+y_1^4-x_1^2x_2^2,$$

with $vol(G_4) \approx 4.39$ much better than - $\pi R^2 = 2\pi \approx 6.28$ for the Löwner-John ellipsoid of minimum volume, and

- the (convex) TV screen $\textbf{G}:=\{\textbf{x}:(x_1^4+x_2^4)/2<=1\}$ with volume >5.

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Let $\mathbf{K} \subset \mathbb{R}^2$ be the box $[-1, 1]^2$.

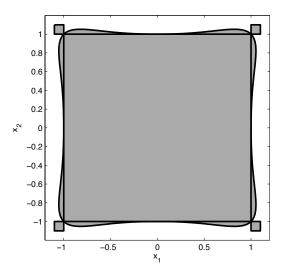
The set $G_6 := \{x : g(x) \le 1\}$ with *g* homogeneous of degree 6 which contains **K** and has minimum volume is

$$\mathbf{x} \mapsto g_6(\mathbf{x}) := x_1^6 + y_1^6 - (x_1^4 x_2^2 + x_1^2 x_2^4)/2,$$

with $vol(G_6) \approx 4.19$ much better than - $\pi R^2 = 2\pi \approx 6.28$ for the Löwner-John ellipsoid of minimum volume, and

- better than the set G_4 with volume 4.39.

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VI. Recovering g from moments of G

Write
$$g(x) = \sum_{\beta} g_{\beta} x^{\beta}$$
.

Lemma

If g is nonnegative and d-homogeneous with G compact then:

$$\underbrace{\int_{G} x^{\alpha} g(x) dx}_{\sum_{\beta} g_{\beta} y_{\alpha+\beta}} = \frac{n+|\alpha|}{n+d+|\alpha|} \underbrace{\int_{G} \mathbf{x}^{\alpha} dx}_{y_{\alpha}}, \qquad \alpha \in \mathbb{N}^{n}.$$

and so we see that the moments (y_{α}) satisfy linear relationships explicit in terms of the coefficients of the polynomial *g* that describes the boundary of *G*.

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So let us write $\mathbf{g} \in \mathbb{R}^{s(d)}$ the unknown vector of coefficients of the unknown polynomial g.

Let $\mathbf{M}_d(\mathbf{y})$ be the moment matrix of order d whose rows and columns are indexed in the canonical basis of monomials (x^{α}) , $\alpha \in \mathbb{N}_d^n$, and with entries

 $\mathbf{M}_{d}(\mathbf{y})(\alpha,\beta) = \mathbf{y}_{\alpha+\beta}, \qquad \alpha,\beta \in \mathbb{N}_{d}^{n}.$

and let \mathbf{y}^d be the vector $(\mathbf{y}_{\alpha}), \alpha \in \mathbb{N}^n_d$.

Previous Lemma states that

 $\mathbf{M}_{\mathbf{d}}(\mathbf{y})\mathbf{g} = \mathbf{y}^{\mathbf{d}},$

or, equivalently,

$$\mathbf{g} = \mathbf{M}_{\mathbf{d}}(\mathbf{y})^{-1} \, \mathbf{y}^{\mathbf{d}},$$

because the moment matrix $\mathbf{M}_d(\mathbf{y})$ is nonsingular whenever *G* has nonempty interior.

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In other words ...

one may recover g EXACTLY from knowledge of moments (y_{α}) of order d and 2d!

Jean B. Lasserre Recovery of algebraic-exponential data from moments

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If g is not quasi-homogeneous then one cannot directly relate

$$\int_{\{\mathbf{x}:g(\mathbf{x})\leq 1\}} d\mathbf{x} \text{ and } \int_{\mathbb{R}^n} \exp(-g(\mathbf{x})) d\mathbf{x}.$$

But still the Laplace transform $\lambda \mapsto F(\lambda)$ of the function

$$\mathbf{y} \mapsto f(\mathbf{y}) := \int_{\{\mathbf{x}: |g(\mathbf{x})| \le \mathbf{y}\}} d\mathbf{x}$$

is the non Gaussian integral

$$\lambda \mapsto F(\lambda) = \frac{1}{\lambda} \int_{\mathbb{R}^n} \exp(-\lambda |g(\mathbf{x})|) d\mathbf{x}.$$

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Nice asymptotic results are available (Vassiliev)

$$f(\mathbf{y}) \approx \mathbf{y}^{\mathbf{a}} \ln(\mathbf{y})^{\mathbf{b}}, \text{ as } \mathbf{y} \rightarrow \infty$$

for some rationals *a*, *b* obtained from the Newton polytope of *g*.

One even has asymptotic results for

$$\mathbf{y} \mapsto \tilde{f}(\mathbf{y}) := \# \left(\{ \mathbf{x} : | \mathbf{g}(\mathbf{x}) | \le \mathbf{y} \} \cap \mathbf{Z}^n \right), \text{ as } \mathbf{y} \to \infty$$

still in the form

$$ilde{f}({m y}) \,pprox\, {m y}^{a'}\,\ln({m y})^{b'}, \quad {
m as}\,\,{m y} \,
ightarrow \infty$$

for some rationals a', b' obtained from the (modified) Newton polytope of g.

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Given a polynomial $g \in \mathbb{R}[\mathbf{x}]_d$ write $g(\mathbf{x}) = \sum_{k=0}^d g_k(\mathbf{x})$, where each g_k is homogeneous of degree k.

Lemma

Let $g \in \mathbb{R}[\mathbf{x}]_d$ be such that its level set $\mathbf{G} := {\mathbf{x} : g(\mathbf{x}) \le 1}$ is bounded. Then for every $\alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}^n$:

$$\int_{\mathbf{G}} \mathbf{x}^{\alpha} (1 - g(\mathbf{x})) \, d\mathbf{x} = \sum_{k=1}^{d} \frac{k}{n + |\alpha|} \int_{\mathbf{G}} \mathbf{x}^{\alpha} g_{k}(\mathbf{x}) \, d\mathbf{x}$$

Observe that for each fixed arbitrary $\alpha \in \mathbb{N}^n$...

One obtains LINEAR EQUALITIES between MOMENTS of the Lebesgue measure on G!

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Observe that for each fixed arbitrary $\alpha \in \mathbb{N}^n$...

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Proof:

Use Stokes' formula

$$\int_{\mathbf{G}} \operatorname{Div}(X) f(\mathbf{x}) \, d\mathbf{x} + \int_{\mathbf{G}} \langle X, \nabla f(\mathbf{x}) \rangle d\mathbf{x} = \int_{\partial \mathbf{G}} \langle X, \vec{n}_{\mathbf{x}} \rangle \, f \, d\sigma,$$

with vector field $X = \mathbf{x}$ and $f(\mathbf{x}) = \mathbf{x}^{\alpha}(1 - \mathbf{g}(\mathbf{x}))$.

• Then observe that Div(X) = n and:

$$\langle X, \nabla f(\mathbf{x}) \rangle = |\alpha| f - \mathbf{x}^{\alpha} \sum_{k=1}^{d} k g_k(\mathbf{x}).$$

 \star In the general case, when ∂G may have singular points, or lower dimensional components, we can invoke Sard's theorem, for the (smooth) sublevel sets

$$G_{\gamma} = \{ \mathbf{x} : g(\mathbf{x}) < \gamma \}$$

and pass to the limit $\gamma o 1, \ \gamma < 1.$

Proof:

• Use Stokes' formula

$$\int_{\mathbf{G}} \operatorname{Div}(X) f(\mathbf{x}) \, d\mathbf{x} + \int_{\mathbf{G}} \langle X, \nabla f(\mathbf{x}) \rangle d\mathbf{x} = \int_{\partial \mathbf{G}} \langle X, \vec{n}_{\mathbf{x}} \rangle \, f \, d\sigma,$$

with vector field $X = \mathbf{x}$ and $f(\mathbf{x}) = \mathbf{x}^{\alpha}(1 - g(\mathbf{x}))$.

• Then observe that Div(X) = n and:

$$\langle X, \nabla f(\mathbf{x}) \rangle = |\alpha| f - \mathbf{x}^{\alpha} \sum_{k=1}^{d} k g_k(\mathbf{x}).$$

 \star In the general case, when ∂G may have singular points, or lower dimensional components, we can invoke Sard's theorem, for the (smooth) sublevel sets

$$G_{\gamma} = \{\, \mathbf{x} : g(\mathbf{x}) < \gamma \,\}$$

and pass to the limit $\gamma \rightarrow 1, \ \gamma < 1.$

Let $\mathbf{G} \subset \mathbb{R}^n$ be open with $\mathbf{G} = \operatorname{int} \overline{\mathbf{G}}$ and with real algebraic boundary $\partial \mathbf{G}$. A polynomial of degree *d* vanishes on $\partial \mathbf{G}$.

Define a renormalised moment-type matrix $M_k^d(\mathbf{y})$ as follows:

-
$$s(d) \ (= \binom{n+d}{n})$$
 columns indexed by $\beta \in \mathbb{N}_d^n$,

- countably many rows indexed by $\alpha \in \mathbb{N}_k^n$, and with entries:

$$\mathbf{M}_{k}^{d}(\mathbf{y})(\alpha,\beta) := \frac{n+|\alpha|+|\beta|}{n+|\alpha|} \mathbf{y}_{\alpha+\beta}, \qquad \alpha \in \mathbb{N}_{k}^{n}, \, \beta \in \mathbb{N}_{d}^{n}.$$

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Theorem

Let $\mathbf{G} \subset \mathbb{R}^n$ be a bounded open set with real algebraic boundary. Assume that $\mathbf{G} = \operatorname{int} \overline{\mathbf{G}}$ and a polynomial of degree d vanishes on $\partial \mathbf{G}$ and not at 0. Then the linear system

$$\mathbf{M}_{2d}^{d}(\mathbf{y})\left[\begin{array}{c}-1\\\mathbf{g}\end{array}\right]=0,$$

admits a unique solution $\mathbf{g} \in \mathbb{R}^{s(d)-1}$, and the polynomial g with coefficients $(0, \mathbf{g})$ satisfies

$$(\mathbf{x} \in \partial G) \Rightarrow (\underline{g}(\mathbf{x}) = 1).$$

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Sketch of the proof

The identity (obtained from Stokes' theorem)

$$\int_{\mathbf{G}} \mathbf{x}^{\alpha} (1 - g(\mathbf{x})) \, d\mathbf{x} = \sum_{k=1}^{d} \frac{k}{n + |\alpha|} \int_{\mathbf{G}} \mathbf{x}^{\alpha} g_{k}(\mathbf{x}) \, d\mathbf{x}$$

for all $\alpha \in \mathbb{N}_k^n$

in fact reads:

$$\mathbf{M}_{k}^{d}(\mathbf{y})\left[\begin{array}{c}-\mathbf{1}\\\mathbf{g}\end{array}\right]=\mathbf{0},$$

Conversely, if g solves

$$\mathbf{M}_{2d}^{d}(\mathbf{y}) \left[\begin{array}{c} -1 \\ \mathbf{g} \end{array} \right] = \mathbf{0},$$

then

$$\langle \mathbf{x}, \vec{n_{\mathbf{x}}} \rangle (1 - g(\mathbf{x})) \mathbf{x}^{\alpha} d\sigma = 0, \quad \forall \alpha \in \mathbb{N}^{n}_{2d}.$$

Jean B. Lasserre Recovery of algebraic-exponential data from moments

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Sketch of the proof

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Jean B. Lasserre

Recovery of algebraic-exponential data from moments

As ∂G is algebraic, one may write

$$\vec{n_{\mathbf{x}}} = \frac{\nabla h(\mathbf{x})}{\|\nabla h(\mathbf{x})\|},$$

for some polynomial h. Therefore

$$0 = \int_{\partial \mathbf{G}} \langle \mathbf{x}, \vec{n_{\mathbf{x}}} \rangle (1 - g(\mathbf{x})) \mathbf{x}^{\alpha} d\sigma \quad \forall \alpha \in \mathbb{N}_{2d}^{n}$$

$$= \int_{\partial \mathbf{G}} \underbrace{\langle \mathbf{x}, \nabla h(\mathbf{x}) \rangle}_{\in \mathbb{R}[\mathbf{x}]_{d}} \underbrace{(1 - g(\mathbf{x}))}_{\in \mathbb{R}[\mathbf{x}]_{d}} \mathbf{x}^{\alpha} \frac{1}{\|\nabla h\|} d\sigma \quad \forall \alpha \in \mathbb{N}_{2d}^{n}$$

$$\Rightarrow \int_{\partial \mathbf{G}} \underbrace{\langle \mathbf{x}, \nabla h(\mathbf{x}) \rangle^{2}}_{\neq 0 \ \sigma - a.e.} (1 - g(\mathbf{x}))^{2} d\sigma' = 0 \quad \Box$$

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For sake of rigor the boundary ∂G can be written

$$\partial \mathbf{G} = Z_0 \cup Z_1,$$

with Z_0 being a finite union of smooth n - 1-submanifolds of \mathbb{R}^n leaving **G** on one side, Z_1 is a union of the lower dimensional strata, and $\sigma(Z_1) = 0$.

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Theorem

Let $\mathbf{G} \subset \mathbb{R}^n$ be a bounded convex open set with real algebraic boundary. Assume that $\mathbf{G} = \operatorname{int} \overline{\mathbf{G}}$, $0 \in \mathbf{G}$, and a polynomial of degree d vanishes on $\partial \mathbf{G}$ and not at 0. Then the linear system

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 \star As in the previous proof, if

$$\mathbf{M}_{d}^{d}(\mathbf{y})\left[egin{array}{c} -1\ \mathbf{g}\end{array}
ight]=\mathbf{0},$$

then

$$\int_{\partial \mathbf{G}} \langle \mathbf{x}, \vec{n_{\mathbf{x}}} \rangle (1 - g(\mathbf{x}))^2 \, d\sigma \, = \, 0.$$

But one now uses that if $0 \in \mathbf{G}$ then $\langle \mathbf{x}, \vec{n_x} \rangle \ge 0$.

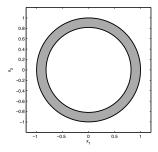
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Example

Let us consider the two-dimensional example of the annulus

$$\textbf{G} \, := \, \{ \, \textbf{x} \in \mathbb{R}^2 : \, 1 - x_1^2 - x_2^2 \geq 0 ; \, x_1^2 + x_2^2 - 2/3 \geq 0 \, \}.$$

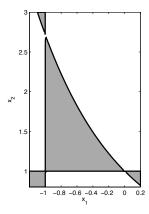


The polynomial $(1 - x_1^2 - x_2^2)(x_1^2 + x_2^2 - 2/3)$ is the unique solution of $\mathbf{M}_4^4(\mathbf{y})[-1, \mathbf{g}] = 0$.

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Example continued: Non-algebraic boundary

Let
$$\mathbf{G} = \{\mathbf{x} \in \mathbb{R}^2 : x_1 \ge -1; x_2 \ge 1; x_2 \le \exp(-x_1)\}.$$



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We now look as the eigenvector g of the smallest eigenvalue of $M_3^3(y)$.

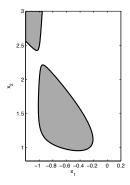


Figure: Shape $\mathbf{G}' = {\mathbf{x} : g(\mathbf{x}) \le 0}$ with d = 3

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We now look as the eigenvector g of the smallest eigenvalue of $\mathbf{M}_4^4(\mathbf{y})$.

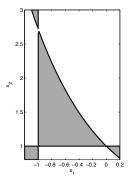


Figure: Shape $\mathbf{G}' = {\mathbf{x} : g(\mathbf{x}) \le 0}$ with d = 4

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uniformly supported on a set *G* of the form $\{\mathbf{x} : g(\mathbf{x}) \le 1\}$, for some polynomial $g \in \mathbb{R}[\mathbf{x}]_d$.

Then :

• ALL moments $y_{\alpha} := \int_{G} \mathbf{x}^{\alpha} d\mu$, $\alpha \in \mathbb{N}^{n}$, are determined from those up to order 3*d* (and 2*d* if *G* is convex) !

• A similar result holds true if now μ has a density $\exp(h(\mathbf{x}))$ on *G* (for some $h \in \mathbb{R}[\mathbf{x}]$).

ightarrow is an extension to such measures of a well-known result for exponential families

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 \rightarrow is an extension to such measures of a well-known result for exponential families

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- Compact sub-level sets $G := \{x : g(x) \le y\}$ of homogeneous polynomials exhibit surprising properties. E.g.:
 - convexity of volume(G) with respect to the coefficients of g
 - Integrating a PHF *h* on *G* reduce to evaluating the non Gaussian integral $\int h \exp(-g) dx$
 - A variational property yields a Gaussian-like property
 - exact recovery of *G* from finitely moments.
 (Also works for quasi-homogeneous polynomials with bounded sublevel sets!)
 - exact recovery for sets with algebraic boundary of known degree

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- COMPUTATION!: Efficient evaluation of $\int_{\mathbb{R}^n} \exp(-g) dx$, or equivalently, evaluation of vol $(\{x : g(x) \le 1\}!$
 - The property

$$\int_{G} \mathbf{x}^{\alpha} g(x) \, dx = \frac{n + |\alpha|}{n + d + |\alpha|} \int_{G} x^{\alpha} \, dx, \qquad \forall \alpha,$$

helps a lot to improve efficiency of the method in Henrion, Lasserre and Savorgnan (SIAM Review)

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- J.B. Lasserre. A Generalization of Löwner-John's ellipsoid Theorem. *Math. Program.*, to appear.
- J.B. Lasserre. Recovering an homogeneous polynomial from moments of its level set. *Discrete & Comput. Geom.* 50, pp. 673–678, 2013.
- J.B. Lasserre and M. Putinar. Reconstruction of algebraic-exponential data from moments. Submitted
- J.B. Lasserre. Unit balls of constant volume: which one has optimal representation? submitted.

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THANK YOU!

Jean B. Lasserre Recovery of algebraic-exponential data from moments

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