
Notes on Probabilistic PCA with Missing Values

Jakob Verbeek
INRIA Rhône-Alpes
Updated March 18, 2009

1 Model

Let $\mathbf{y} \in \mathbb{R}^D$ denote a data vector $\mathbf{x} \in \mathbb{R}^d$ denote the vector of principal component coordinates, we let

$$p(\mathbf{x}) = \mathcal{N}(\mathbf{x}; 0, \mathbf{I}), \quad (1)$$

$$p(\mathbf{y}|\mathbf{x}) = \mathcal{N}(\mathbf{y}; C^\top \mathbf{x}, \sigma^2 \mathbf{I}), \quad (2)$$

where C is a $d \times D$ matrix with the projection vectors from the principal component coordinates to the data coordinates. The conditional on \mathbf{x} given \mathbf{y} is then given by

$$p(\mathbf{x}|\mathbf{y}) = \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}, \Sigma), \quad (3)$$

$$\boldsymbol{\mu} = \sigma^{-2} \Sigma C \mathbf{y}, \quad (4)$$

$$\Sigma^{-1} = \mathbf{I} + \sigma^{-2} C C^\top. \quad (5)$$

When only a subset of the coordinates of \mathbf{y} is observed, we replace C above with the C_o which has only the columns corresponding to the observed values, and similar for \mathbf{y} which is replaced by the observed part \mathbf{y}_o .

Our goal is now to find the parameters C and σ that maximize the likelihood of some observed data: vectors \mathbf{y} that are fully or partially observed. To do so, we use an EM algorithm that estimates in the E-step the missing values: the vectors \mathbf{x} and the missing parts of the \mathbf{y} which we denote by \mathbf{y}_h . In the M-step we fix these estimates, and maximize the expected joint log-likelihood of \mathbf{x} and \mathbf{y} .

For simplicity we assume that the distribution over \mathbf{x} and \mathbf{y}_h factors so that we write a lower-bound on the data log-likelihood as

$$\log p(\mathbf{y}_o) \geq \log p(\mathbf{y}_o) - D(q(\mathbf{x})q(\mathbf{y}_h)||p(\mathbf{x}, \mathbf{y}_h|\mathbf{y}_o)) \quad (6)$$

$$= H(q(\mathbf{x})) + H(q(\mathbf{y}_h)) + \mathbb{E}_q[\log p(\mathbf{x}) + \log p(\mathbf{y}|\mathbf{x})] \quad (7)$$

We will now maximize this bound, in the E-step with respect to the distributions q , and in the M-step with respect to the parameters.

2 E-step

From the above we find the optimal distributions q as

$$q(\mathbf{y}_h) \propto \exp \int q(\mathbf{x}) \log p(\mathbf{y}_h|\mathbf{x}) = \mathcal{N}(\mathbf{y}_h; C_h^\top \bar{\mathbf{x}}, \sigma^2 \mathbf{I}), \quad (8)$$

$$q(\mathbf{x}) \propto p(\mathbf{x}|\mathbf{y}_o) \exp \int q(\mathbf{y}_h) \log p(\mathbf{y}_h|\mathbf{x}) = \mathcal{N}(\mathbf{x}; \sigma^{-2} \Sigma C \bar{\mathbf{y}}, \Sigma), \quad (9)$$

where $\bar{\mathbf{y}}$ is the mean of $q(\mathbf{y}_h)$ for the missing values and \mathbf{y}_o for the observed part, and $\bar{\mathbf{x}}$ is the mean of $q(\mathbf{x})$.

3 M-step

The expectation in Eq. (7), summed over N data, can be expanded as

$$\sum_{n=1}^N \mathbb{E}_{q_n} [\log p(\mathbf{x}_n) + \log p(\mathbf{y}_n|\mathbf{x}_n)] = \quad (10)$$

$$-\frac{ND}{2} \log \sigma^2 - \frac{1}{2\sigma^2} \left(\sum_n \|\bar{\mathbf{y}}_n - C^\top \bar{\mathbf{x}}_n\|^2 - \text{Tr}\{C^\top \Sigma C\} \right) - \frac{D_h}{2\sigma^2} \sigma_{\text{old}}^2 \quad (11)$$

$$-\frac{1}{2} \sum_n \|\bar{\mathbf{x}}_n\|^2 - \frac{N}{2} \text{Tr}\{\Sigma\} \quad (12)$$

where D_h denotes the total number of missing values, and σ_{old} is the current value of σ that was used in the E-step to compute the q .

Maximizing this over C and σ we get

$$C = (N\Sigma + \bar{X}\bar{X}^\top)^{-1} \bar{X}\bar{Y}^\top, \quad (13)$$

$$\sigma^2 = \frac{1}{ND} \left(N\text{Tr}\{C^\top \Sigma C\} + \sum_n \|\bar{\mathbf{y}}_n - C^\top \bar{\mathbf{x}}_n\|^2 + D_h \sigma_{\text{old}}^2 \right), \quad (14)$$

where \bar{X} and \bar{Y} denote matrices that collect all $\bar{\mathbf{x}}$ and $\bar{\mathbf{y}}$ as columns.

4 Objective function

Given the expansion of Eq. (7) above, we only need the expression for the entropy of a Gaussian to calculate the EM bound of Eq. (7). It is well known that the entropy for a Gaussian with covariance matrix Σ , for fixed dimensionality, is given up to an additive constant by

$$H = \frac{1}{2} \log |\Sigma|. \quad (15)$$

Combining this with the equations for the parameters found in the M-step, we have that after performing the M-step the bound is calculated as:

$$\log p(\mathbf{y}_o) \geq -\frac{ND}{2} (1 + \log \sigma^2) - \frac{N}{2} (\text{Tr}\{\Sigma\} - \log |\Sigma|) - \frac{1}{2} \sum_n \|\mathbf{x}_n\|^2 + \frac{D_h}{2} \log \sigma_{\text{old}}^2.$$

See [1] for the Gaussian identities used in this derivation.

References

- [1] S. Roweis. Gaussian identities. Online notes, see <http://www.cs.toronto.edu/~roweis/notes.html>.