

## NESTA: a fast and accurate first-order method for sparse recovery

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Applied and Computational Mathematics 2009

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Grenoble, April 24, 2014

# Introduction

- Algorithm NESTA
- Optimization based on Nesterov's method
- Compressed sensing applications (e.g. sparse recovery, Total Variation minimization)
- Accurate retrieval of the signal
- Large scale - e.g.  $x \in \mathbb{R}^n$  with,  $n = 262\,144$

$$\begin{array}{ll} (\text{BP}_\epsilon) & \text{minimize} & \|x\|_{\ell_1} \\ & \text{subject to} & \|b - Ax\|_{\ell_2} \leq \epsilon, \end{array}$$

A consequence of these properties is that NESTA may be interest of researchers working on signal recovery or undersampled data

# Optimization

Problem to solve with NESTA:

$$\begin{aligned} (\text{BP}_\epsilon) \quad & \text{minimize} && \|x\|_{\ell_1} \\ & \text{subject to} && \|b - Ax\|_{\ell_2} \leq \epsilon, \end{aligned}$$

Equivalent formulation:

$$(\text{QP}_\lambda) \quad \text{minimize} \quad \lambda \|x\|_{\ell_1} + \frac{1}{2} \|b - Ax\|_{\ell_2}^2,$$

$\|\cdot\|_{\ell_1} \rightarrow$  a sparse solution;  $\epsilon^2 =$  estimated bound on noise

where

$b = Ax^0 + z$ : collected data

$x^0$ : signal to recover

$A$ : sampling matrix

$z$ : noise



source: G. Peyré OSL2013

## Nesterov's method

$$\min_{x \in \mathcal{Q}_p} f(x)$$

$f$  : smooth, i.e. differentiable with Lipschitz gradient

$\mathcal{Q}_p$  : convex set

Lipschitz gradient of  $f$ , with lipschitz constant  $L$ :

$$\forall x, y \in \mathcal{Q}_p \quad \|\nabla f(y) - \nabla f(x)\|_{\ell_2} \leq L \|y - x\|_{\ell_2}$$

[ Y. NESTEROV, *Smooth minimization of nonsmooth functions*, Math. Program. (2005)]

# Nesterov's method

**Initialize**  $x_0$ . For  $k \geq 0$ ,

1. Compute  $\nabla f(x_k)$ .

2. Compute  $y_k$ :

$$y_k = \operatorname{argmin}_{x \in Q_p} \frac{L}{2} \|x - x_k\|_{\ell_2}^2 + \langle \nabla f(x_k), x - x_k \rangle.$$

3. Compute  $z_k$ :

$$z_k = \operatorname{argmin}_{x \in Q_p} \frac{L}{\sigma_p} p_p(x) + \sum_{i=0}^k \alpha_i \langle \nabla f(x_i), x - x_i \rangle.$$

4. Update  $x_k$ :

$$x_k = \tau_k z_k + (1 - \tau_k) y_k.$$

**Stop** when a given criterion is valid.

$p_p$ : continuous and strongly convex,  $p_p(x) \geq \frac{\sigma_p}{2} \|x - x_p^c\|^2$

What if  
 $f$   
is nonsmooth?

# Smoothing

We can rewrite the norm as support function

$$\|x\|_{\ell_1} = \max_{u \in \mathcal{Q}_d} \langle u, x \rangle,$$

where

$$\mathcal{Q}_d = \{u : \|u\|_{\infty} \leq 1\}.$$

The smoothed version of  $\|\cdot\|_{\ell_1}$  is

$$f_{\mu}(x) = \max_{u \in \mathcal{Q}_d} \langle u, x \rangle - \mu p_d(u),$$

## Theorem

*If  $p_d$  is continuous and strongly convex on  $\mathcal{Q}_d$ , then  $f_{\mu}$  is smooth.*

Then it is possible to apply Nesterov method to  $f_{\mu}$

[Y. NESTEROV, Smooth minimization of nonsmooth functions, Math. Program. (2005)]

NESTA = Nesterov method + smoothing

Convergence of NESTA:

$$f_{\mu}(y_k) - f_{\mu}(x_{\mu}^*) \leq \frac{2L_{\mu}\|x_{\mu}^* - x_0\|_{\ell_2}^2}{k^2},$$

$k$  : iteration counter

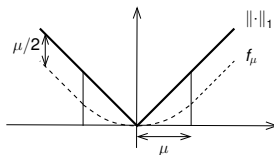
$x_{\mu}^* := \operatorname{argmin}_{x \in Q_{\rho}} f_{\mu}(x)$

$L_{\mu}$  : Lipschitz constant of  $f_{\mu}$



The parameter  $\mu$  controls the smoothing

$$f_{\mu}(x) = \max_{u \in \mathcal{Q}_d} \langle u, x \rangle - \mu p_d(u),$$



Source: Pierucci, Harchaoui, Malick, tech. report 2014

Small  $\mu \rightarrow$  good approximation, slow convergence  
Large  $\mu \rightarrow$  worst approximation, faster convergence

Why don't we  
start with a  
large  $\mu$

and continue with a  
smaller  $\mu$   
?

## NESTA “with continuation”

**Initialize**  $\mu_0$ ,  $x_0$  and the number of continuation steps  $T$ . For  $t \geq 1$ ,

1. Apply Nesterov's algorithm with  $\mu = \mu^{(t)}$  and  $x_0 = x_{\mu^{(t-1)}}$ .
2. Decrease the value of  $\mu$ :  $\mu^{(t+1)} = \gamma\mu^{(t)}$  with  $\gamma < 1$ .

**Stop** when the desired value of  $\mu_f$  is reached.

## Convergence of NESTA with continuation

**THEOREM 3.1.** *At each continuation step  $t$ ,  $\lim_{k \rightarrow \infty} y_k = x_{\mu^{(t)}}^*$ , and*

$$f_{\mu^{(t)}}(y_k) - f_{\mu^{(t)}}(x_{\mu^{(t)}}^*) \leq \frac{2L_{\mu^{(t)}} \|x_{\mu^{(t)}}^* - x_{\mu^{(t-1)}}\|_{\ell_2}^2}{k^2}.$$

## Accuracy evaluation

Analytical solution only for particular cases  $\rightarrow$  FISTA

$$(\text{QP}_\lambda) \quad \text{minimize} \quad \lambda \|x\|_{\ell_1} + \frac{1}{2} \|b - Ax\|_{\ell_2}^2,$$

Relative error on objective function

$$\frac{\|x\|_{\ell_1} - \|x^*\|_{\ell_1}}{\|x^*\|_{\ell_1}}$$

Accuracy of optimal solution

$$\ell_\infty \text{ error} := \|x - x^*\|_{\ell_\infty}$$

TABLE 4.2

*NESTA's accuracy. The errors and number of function calls  $\mathcal{N}_A$  have the same meaning as in Table 4.1.*

| Method              | $\ell_1$ -norm | Rel. error $\ell_1$ -norm | $\ell_\infty$ error | $\mathcal{N}_A$ |
|---------------------|----------------|---------------------------|---------------------|-----------------|
| FISTA               | 5.71539e+7     |                           |                     |                 |
| NESTA $\mu = 0.2$   | 5.71614e+7     | 1.3e-4                    | 3.8                 | 659             |
| NESTA $\mu = 0.02$  | 5.71547e+7     | 1.4e-5                    | 0.96                | 1055            |
| NESTA $\mu = 0.002$ | 5.71540e+7     | 1.6e-6                    | 0.64                | 1537            |

$x^*$ : optimal solution for  $\text{BP}_\epsilon$

# Results

TABLE 5.2

Number of function calls  $N_A$  averaged over 10 independent runs. The sparsity level  $s = m/5$  and the stopping rule is Crit. 2 (5.2).

| Method      | 20 dB       | 40 dB       | 60 dB          | 80 dB          | 100 dB            |
|-------------|-------------|-------------|----------------|----------------|-------------------|
| NESTA       | 446 351/491 | 880 719/951 | 1701 1581/1777 | 4528 4031/4749 | 14647 7729/15991  |
| NESTA + Ct  | 479 475/485 | 551 539/559 | 605 589/619    | 658 635/679    | 685 657/705       |
| GPSR        | 59 44/64    | 736 678/790 | 5316 4814/5630 | DNC            | DNC               |
| GPSR + Ct   | 305 293/311 | 251 245/257 | 511 467/543    | 1837 1323/2091 | 9127 7251/10789   |
| SpaRSA      | 345 327/373 | 455 435/469 | 541 509/579    | 600 561/629    | 706 667/819       |
| SPGL1       | 55 37/61    | 138 113/152 | 217 196/233    | 358 300/576    | 470 383/568       |
| FISTA       | 65 63/66    | 288 279/297 | 932 882/966    | 3407 2961/3591 | 13160 11955/13908 |
| FPC AS      | 176 169/183 | 236 157/263 | 218 215/239    | 344 247/459    | 330 319/339       |
| FPC AS (CG) | 357 343/371 | 475 301/538 | 434 423/481    | 622 435/814    | 588 573/599       |
| FPC         | 416 398/438 | 435 418/446 | 577 558/600    | 899 788/962    | 3866 1938/4648    |
| FPC-BB      | 149 140/154 | 172 164/174 | 217 208/254    | 262 248/286    | 512 308/790       |
| Bregman-BB  | 211 203/225 | 270 257/295 | 364 355/393    | 470 429/501    | 572 521/657       |

Dynamic range of a signal  $x$  is  $\log_{10} \left( \frac{x_{max}}{x_{min}} \right)$ , measured in decibel

## Conclusion

$$\begin{array}{ll} (\text{BP}_\epsilon) & \text{minimize} & \|x\|_{\ell_1} \\ & \text{subject to} & \|b - Ax\|_{\ell_2} \leq \epsilon, \end{array}$$

- Nesterov's method
- NESTA
- NESTA with continuation
- Comparison with FISTA
- Compressed sensing applications
- Accurate retrieval of the signal
- Large scale

Thank you for your attention

## Observation on NESTA with continuation:

### Convergence

THEOREM 3.1. *At each continuation step  $t$ ,  $\lim_{k \rightarrow \infty} y_k = x_{\mu^{(t)}}^*$ , and*

$$f_{\mu^{(t)}}(y_k) - f_{\mu^{(t)}}(x_{\mu^{(t)}}^*) \leq \frac{2L_{\mu^{(t)}} \|x_{\mu^{(t)}}^* - x_{\mu^{(t-1)}}\|_{\ell_2}^2}{k^2}.$$

$\gamma < 1$

$L_{\mu}$  is proportional to  $\frac{1}{\mu}$ .

If we take  $\mu^{(t)} = \gamma^t \mu_0$  we have  $\frac{L_{\mu^{(t)}}}{k^2} \propto \frac{1}{\gamma^t k^2}$ . Then the Lipschitz constant grows faster than  $k^2$ . If  $t(k) = k$  there is no evident convergence. We conclude that the convergence proof is valid only if the decreasing value of  $\mu$  is lower bounded.